

Parallel grippers HGPD, sealed

FESTO



Key features

At a glance

General

The fully encapsulated gripper kinematics enable the gripper to be used in extremely harsh ambient conditions. The sturdy and precise kinematics provide maximum torque resistance and a long service life.

The force generated by the linear motion is translated into the gripper jaw movement via a wedge mechanism with force-guided motion.

This also guarantees synchronous movement of the gripper jaws. The virtually backlash-free plain-bearing guide is realised using ground-in gripper jaws.

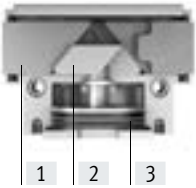
Flexible range of applications

- Can be used as a double-acting and single-acting gripper
- Compression spring for supplementing or retaining the gripping forces
- Suitable for external and internal gripping

The technology in detail

Gripper closed

Gripper open



- [1] Gripper jaw
- [2] Wedge with forced guidance
- [3] Piston with magnet

Note

Engineering software

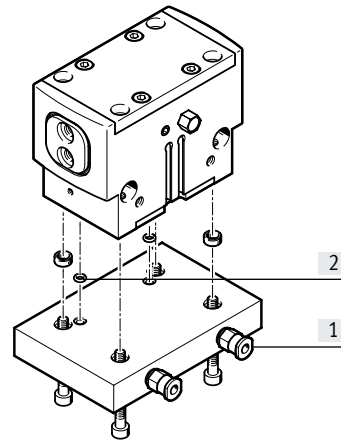
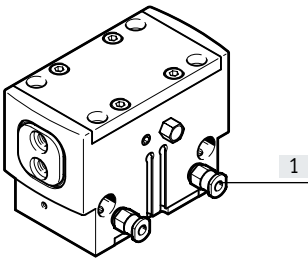
Gripper selection

→ www.festo.com

Wide range of supply ports

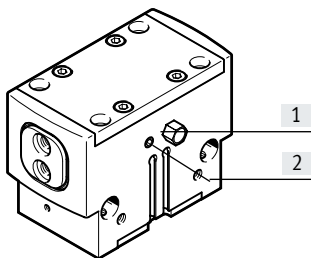
Directly from the front

Via adapter plate from underneath



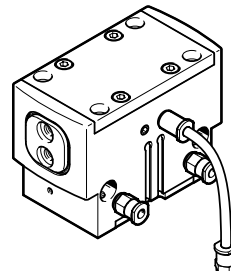
- [1] Supply ports
- [2] O-rings

Other connections



- [1] Exhaust hole or sealing air connection
- [2] Port for lubrication nipple

Use in harsh ambient conditions



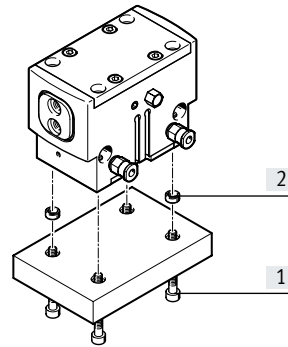
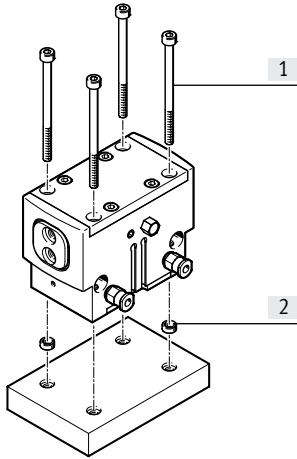
When using the gripper in humid environments or with liquid/gaseous media, make sure that the filter is installed in a neutral environment. The same applies to unused supply ports when operating the gripper as a single-acting gripper.

Key features

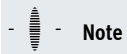
Mounting options

Direct mounting
from above

Via adapter plate
from underneath



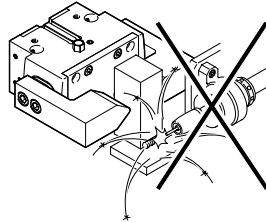
[1] Mounting screws
[2] Centring sleeves



Note

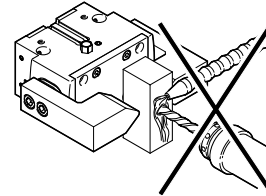
These grippers are not suitable or are of limited suitability for the following application examples:

Not suitable for:

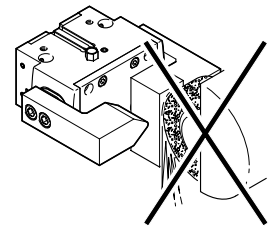


- Welding spatter

Of limited suitability for:



- Aggressive media: only possible after consultation with Festo



- Grinding dust

Parallel grippers HGPD, sealed

Type codes and peripherals overview

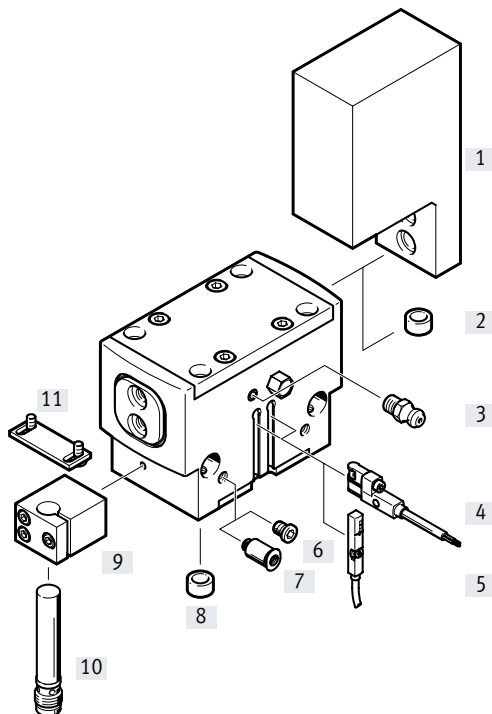
| | | |
|------|--------------------------|--|
| 001 | Series | |
| HGPD | Parallel gripper, sealed | |

| | | |
|-----|------|--|
| 002 | Size | |
| 16 | 16 | |
| 20 | 20 | |
| 25 | 25 | |
| 35 | 35 | |
| 40 | 40 | |
| 50 | 50 | |
| 63 | 63 | |
| 80 | 80 | |

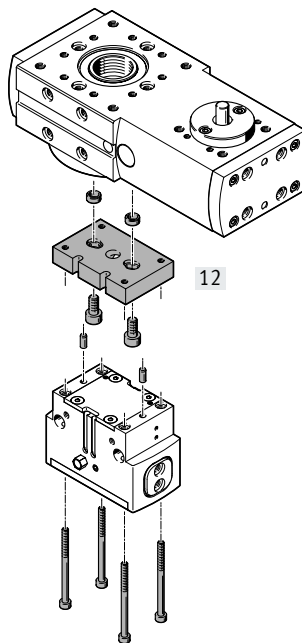
| | | |
|-----|----------------------|--|
| 003 | Position sensing | |
| A | For proximity sensor | |

| | | |
|-----|-----------------------|--|
| 004 | Gripping force backup | |
| | None | |
| G1 | Opening | |
| G2 | N/O contact | |

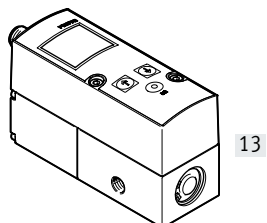
Peripherals overview



System product for handling and assembly technology



Proportional-pressure regulator VPPM

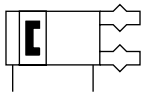


Peripherals overview

| Accessories | | |
|--|---|-----------------|
| Type | Description | → Page/Internet |
| [1] Gripper jaw blank BUB-HGPD | Unmachined part specially matched to the gripper jaws for custom production of gripper fingers | 20 |
| [2] Centring pin/sleeve ZBS/ZBH | <ul style="list-style-type: none"> • For centring the gripper jaw blanks/gripper fingers on the gripper jaws • 4 centring pins/sleeves included in the scope of delivery of the gripper | 21 |
| [3] Lubrication nipple | Included in the scope of delivery of the gripper | - |
| [4] Proximity switch SMT-8G/-10G | <ul style="list-style-type: none"> • For sensing the piston position • Proximity switch does not project past the housing at the bottom | 22 |
| [6] Blanking plug B | For sealing the supply ports when using the lower supply ports | 21 |
| [7] Push-in fitting QS | For connecting tubing with standard O.D. | qs |
| [8] Centring sleeve ZBH | For centring the gripper during mounting | 21 |
| [9] Sensor bracket DASI | Terminal block for securing the proximity switches SIEH or SIEN | 21 |
| [10] Proximity switch SIEH/SIEN | For sensing the piston position | 22 |
| [11] Sensor bracket DASI | Switch lug for sensing the gripper jaw position. Mounted on the gripper jaw blank | 21 |
| [12] Adapter kit DHAA, HAPG | Connecting plate between drive and gripper | 17 |
| [13] Proportional-pressure regulator VPPM | For infinite adjustment of the gripping force | vppm |

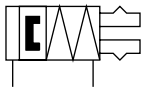
Data sheet

Double-acting
HGPD-...-A



with gripping force retention

HGPD-...-G1 (opening)



HGPD-...-G2 (closing)



⊘ - Size
16 ... 80

— - Total stroke
6 ... 40 mm



www.festo.com



| General technical data | | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 | |
|--|------|---|--------|-----|--------|-----|------|------|------|--|
| Size | | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 | |
| Design | | Wedge mechanism Force-guided motion | | | | | | | | |
| Mode of operation | | Double-acting | | | | | | | | |
| Gripper function | | Parallel | | | | | | | | |
| Number of gripper jaws | | 2 | | | | | | | | |
| Max. mass per gripper finger ¹⁾ | [g] | 25 | 57 | 138 | 278 | 445 | 813 | 1340 | 2170 | |
| Stroke per gripper jaw | [mm] | 3 | 4 | 6 | 8 | 10 | 12 | 16 | 20 | |
| Pneumatic connection | | M5 | M5 | M5 | M5 | M5 | G1/8 | G1/8 | G1/4 | |
| Pneumatic connection, sealing air | | M3 | M3 | M5 | M5 | M5 | M5 | M5 | M5 | |
| Pneumatic connection, lubrication nipple | | M3 | M3 | M5 | M5 | M5 | M5 | M5 | M5 | |
| Repetition accuracy ²⁾ | [mm] | ≤ 0.03 | ≤ 0.04 | | ≤ 0.05 | | | | | |
| Max. interchangeability | [mm] | ≤ ±0.2 | | | | | | | | |
| Max. operating frequency | [Hz] | ≤ 3 | | | | | ≤ 2 | | | |
| Rotational symmetry | [mm] | < ∅ 0.2 | | | | | | | | |
| Position sensing | | Via proximity switch, position transmitter | | | | | | | | |
| Type of mounting | | Via through-hole and dowel pin/centring sleeve Via female thread and dowel pin/centring sleeve | | | | | | | | |
| Mounting position | | Any | | | | | | | | |

1) Applies to unthrottled operation

2) Under constant exposure to operating conditions, end-position drift occurs in the direction of movement of the gripper jaws, at 100 consecutive strokes

Operating and environmental conditions

| | | |
|--|-------|--|
| Min. operating pressure | | |
| HGPD-...-A | [bar] | 3 |
| HGPD-...-A-G | [bar] | 4 |
| Max. operating pressure | [bar] | 8 |
| Operating pressure for sealing air | [bar] | 0 ... 0.5 |
| Operating medium | | Compressed air to ISO 8573-1:2010 [7:4:4] |
| Note on the operating/pilot medium | | Lubricated operation possible (in which case lubricated operation will always be required) |
| Ambient temperature ¹⁾ | [°C] | +5 ... +60 |
| Degree of protection | | IP65 |
| Corrosion resistance class CRC ²⁾ | | 2 |

1) Note operating range of proximity switches

2) Corrosion resistance class CRC 2 to Festo standard FN 940070

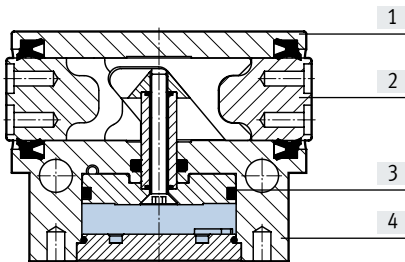
Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

Data sheet

| Weight [g] | | | | | | | | |
|--------------|-----|-----|-----|-----|------|------|------|------|
| Size | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 |
| HGPD-...-A | 100 | 163 | 327 | 572 | 1044 | 1766 | 3365 | 6252 |
| HGPD-...-A-G | 117 | 182 | 361 | 682 | 1223 | 2150 | 3998 | 7484 |

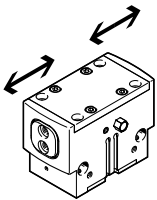
Materials

Sectional view



| Size | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 |
|---------------------|----------------------------|----|----|----|----|----|----|----|
| [1] Cover cap | High-alloy stainless steel | | | | | | | |
| [2] Gripper jaw | Hardened steel | | | | | | | |
| [3] Piston | Hard-anodised aluminium | | | | | | | |
| [4] Housing | Anodised aluminium | | | | | | | |
| - Seals | Nitrile rubber | | | | | | | |
| - Note on materials | Free of copper and PTFE | | - | | | | | |
| | RoHS-compliant | | | | | | | |

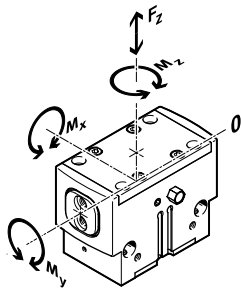
Gripping force [N] at 6 bar



| Size | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 | |
|---------------------------------------|---------|-----|-----|-----|-----|-----|-----|------|------|
| Gripping force per gripper jaw | | | | | | | | | |
| HGPD-...-A | Opening | 54 | 80 | 144 | 291 | 315 | 472 | 967 | 1961 |
| | Closing | 47 | 75 | 133 | 267 | 267 | 447 | 928 | 1858 |
| Total gripping force | | | | | | | | | |
| HGPD-...-A | Opening | 107 | 159 | 288 | 581 | 630 | 944 | 1935 | 3922 |
| | Closing | 94 | 150 | 266 | 534 | 598 | 894 | 1856 | 3716 |

Data sheet

Characteristic load values at the gripper jaws

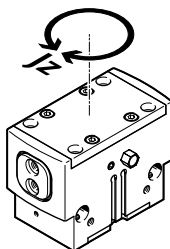


The indicated permissible forces and torques apply to a single gripper jaw. They include the lever arm, additional weight forces due to the workpiece or external gripper fingers and acceleration forces occurring during movement.

The zero coordinate line (gripper jaw guide) must be taken into consideration when calculating torques.

| Size | | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 |
|-------------------------------|------|-----|-----|-----|-----|------|------|------|------|
| Max. permissible force F_z | [N] | 150 | 250 | 500 | 750 | 1200 | 2000 | 3000 | 6000 |
| Max. permissible torque M_x | [Nm] | 8 | 12 | 30 | 40 | 70 | 90 | 120 | 170 |
| Max. permissible torque M_y | [Nm] | 4 | 7 | 25 | 30 | 45 | 60 | 80 | 130 |
| Max. permissible torque M_z | [Nm] | 3 | 6 | 15 | 25 | 35 | 50 | 65 | 110 |

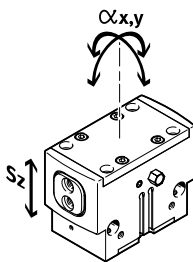
Mass moments of inertia [kgcm²]



Mass moment of inertia of the parallel gripper in relation to the central axis, without external gripper fingers, without load.

| Size | | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 |
|--------------|--|------|------|------|------|-------|-------|--------|--------|
| HGPD-...-A | | 0.22 | 0.40 | 1.32 | 3.56 | 10.10 | 26.19 | 80.33 | 236.48 |
| HGPD-...-A-G | | 0.27 | 0.52 | 1.72 | 4.88 | 14.09 | 36.74 | 116.19 | 319.95 |

Gripper jaw backlash



The plain-bearing guide used in the grippers means that there is backlash between the gripper jaws and the housing. The backlash values listed in the table have been calculated based on the traditional accumulative tolerance method.

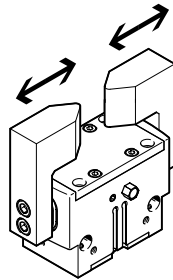
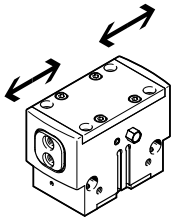
| Size | | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 |
|--|------|------|----|----|----|----|----|----|----|
| Max. gripper jaw backlash S_z | [mm] | 0.02 | | | | | | | |
| Max. gripper jaw angular backlash α_x, α_y | [°] | 0.1 | | | | | | | |

Data sheet

Opening and closing times [ms] at 6 bar

Without external gripper fingers

With external gripper fingers



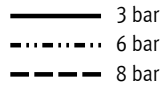
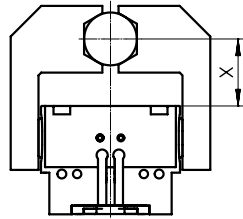
The indicated opening and closing times [ms] were measured at room temperature at an operating pressure of 6 bar with a horizontally mounted gripper without additional gripper fingers. The grippers must be throttled for larger masses [g]. Opening and closing times must then be adjusted accordingly.

| Size | | 16 | 20 | 25 | 35 | 40 | 50 | 63 | 80 |
|---|---------|----|----|----|----|-----|-----|-----|-----|
| Without external gripper fingers | | | | | | | | | |
| HGPD-...-A | Opening | 15 | 28 | 29 | 33 | 73 | 90 | 150 | 214 |
| | Closing | 17 | 31 | 35 | 37 | 77 | 100 | 162 | 218 |
| HGPD-...-A-G1 | Opening | 15 | 13 | 24 | 31 | 73 | 85 | 170 | 235 |
| | Closing | 32 | 25 | 51 | 62 | 157 | 176 | 328 | 353 |
| HGPD-...-A-G2 | Opening | 30 | 35 | 48 | 50 | 143 | 170 | 294 | 379 |
| | Closing | 15 | 18 | 28 | 36 | 71 | 87 | 185 | 240 |
| With external gripper fingers (as a function of the mass per gripper finger) | | | | | | | | | |
| HGPD-... | 50 g | 20 | - | - | - | - | - | - | - |
| | 100 g | 28 | 26 | - | - | - | - | - | - |
| | 200 g | 40 | 37 | 30 | - | - | - | - | - |
| | 300 g | - | 46 | 37 | 34 | - | - | - | - |
| | 400 g | - | - | 43 | 40 | 46 | - | - | - |
| | 500 g | - | - | - | 55 | 52 | - | - | - |
| | 600 g | - | - | - | - | 57 | - | - | - |
| | 800 g | - | - | - | - | 66 | 125 | - | - |
| | 1000 g | - | - | - | - | - | 133 | - | - |
| | 1200 g | - | - | - | - | - | 140 | - | - |
| | 1500 g | - | - | - | - | - | - | 183 | - |
| | 1800 g | - | - | - | - | - | - | 201 | - |
| | 2000 g | - | - | - | - | - | - | 211 | 259 |
| | 2200 g | - | - | - | - | - | - | - | 272 |
| | 2400 g | - | - | - | - | - | - | - | 284 |

Data sheet

Gripping force F_H per gripper jaw as a function of operating pressure and lever arm x

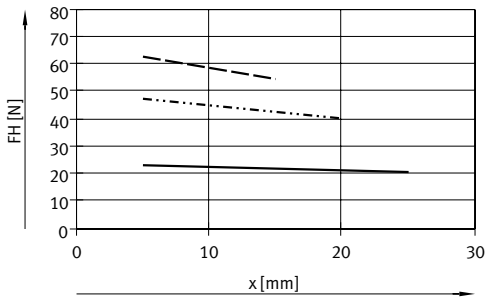
The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.



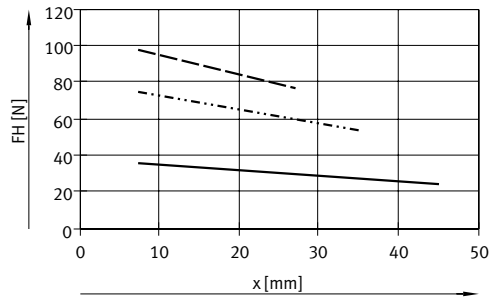
Note
 Engineering software
 Gripper selection
 → www.festo.com

External gripping (closing)

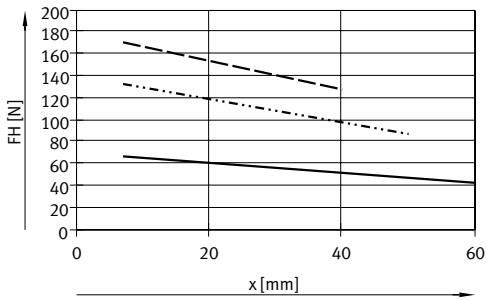
HGPD-16-A



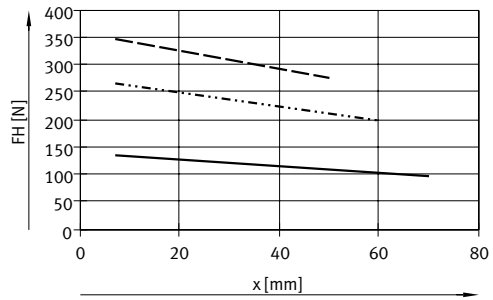
HGPD-20-A



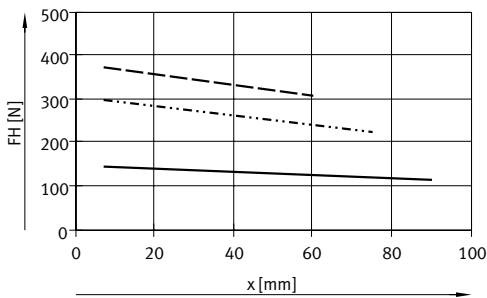
HGPD-25-A



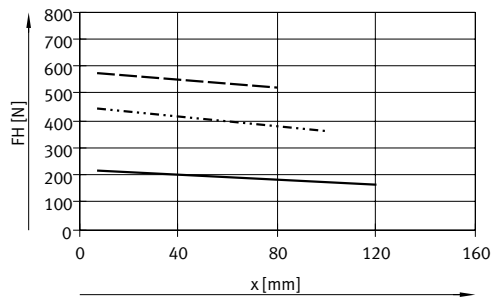
HGPD-35-A



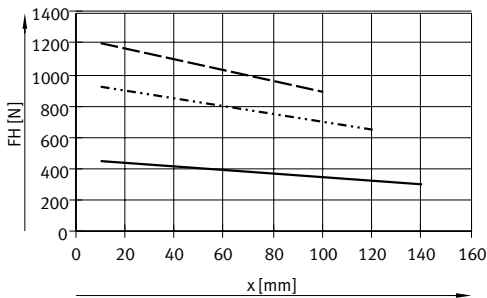
HGPD-40-A



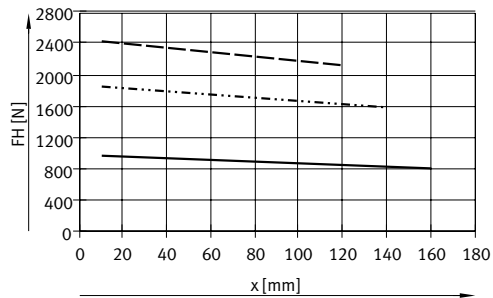
HGPD-50-A



HGPD-63-A



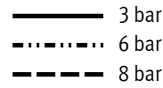
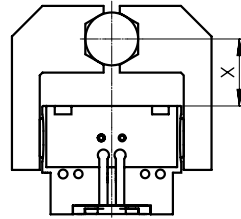
HGPD-80-A



Data sheet

Gripping force F_H per gripper jaw as a function of operating pressure and lever arm x

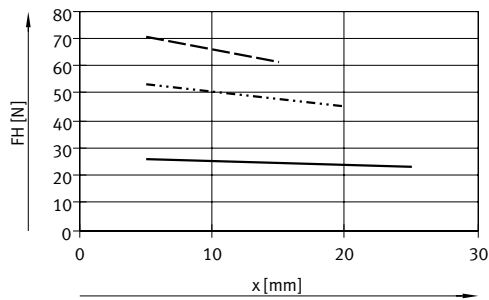
The gripping forces as a function of the operating pressure and lever arm can be determined from the following graphs.



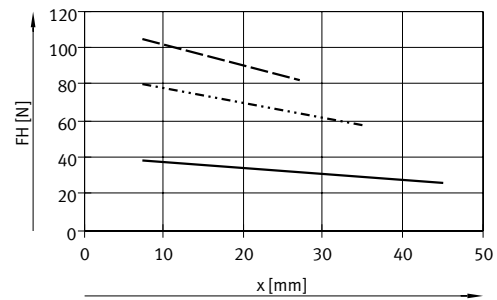
Note
 Engineering software
 Gripper selection
 → www.festo.com

Internal gripping (opening)

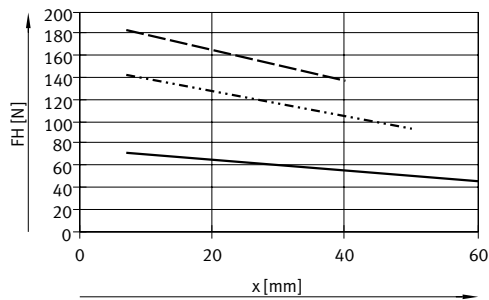
HGPD-16-A



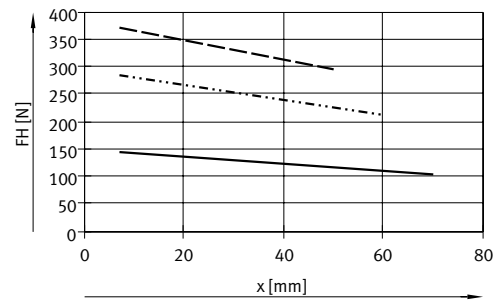
HGPD-20-A



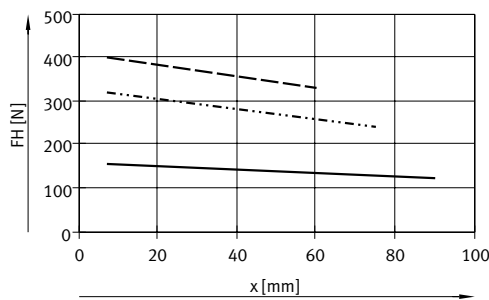
HGPD-25-A



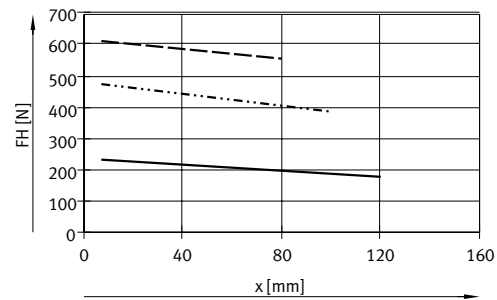
HGPD-35-A



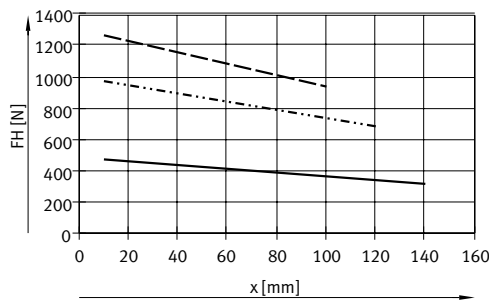
HGPD-40-A



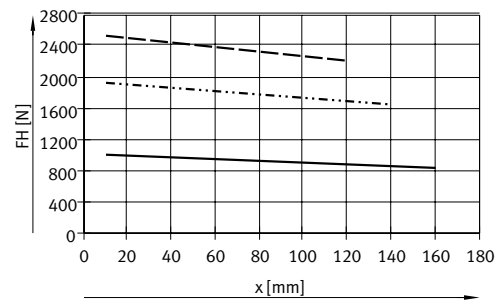
HGPD-50-A



HGPD-63-A



HGPD-80-A



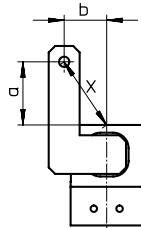
Data sheet

Gripping force F_H per gripper jaw at 6 bar as a function of lever arm x and eccentricity a and b

The following formula must be used to calculate the lever arm x with eccentric gripping:

$$x = \sqrt{a^2 + b^2}$$

The gripping force F_H can be read from the graphs (→ page 10) using the calculated value x .



Calculation example

Assuming:

Distance $a = 45$ mm

Distance $b = 40$ mm

Required:

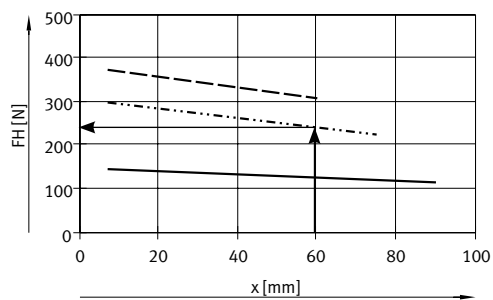
The gripping force at 6 bar with an HGPD-40, used as an external gripper

Procedure: Calculating the lever arm x

$$x = \sqrt{45^2 + 40^2}$$

$$x = 60$$
 mm

The graph (→ page 10) gives a value of $F_H = 240$ N for the gripping force.

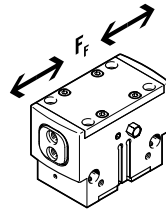


Data sheet

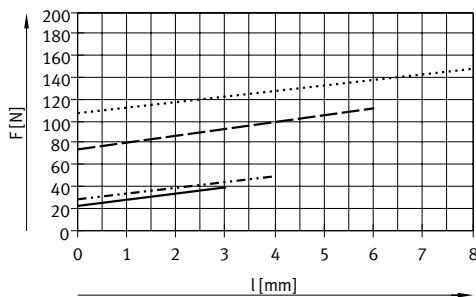
Spring force F_F as a function of size and gripper jaw stroke l

Gripping force retention for HGPD-...-G...

The spring forces F_F as a function of gripper jaw stroke l can be determined from the following graph.

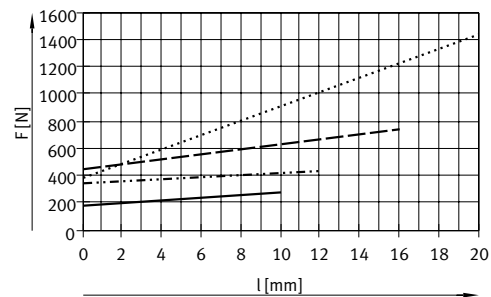


HGPD-16 ... 35



- HGPD-16-A-G
- · - · - · HGPD-20-A-G
- - - - - HGPD-25-A-G
- · · · · HGPD-32-A-G

HGPD-40 ... 80



- HGPD-40-A-G
- · - · - · HGPD-50-A-G
- - - - - HGPD-63-A-G
- · · · · HGPD-80-A-G

Spring force F_F as a function of size, gripper jaw stroke l and lever arm x per gripper finger

The lever arm x must be taken into consideration when determining the actual spring force F_{Ftotal} .

The formulae for calculating the spring force are provided in the table below.

| Gripping force retention | Size | F_{Ftotal} per gripper finger |
|--------------------------|--------------------------------|---------------------------------|
| G1 | 16 | $-0.25 \cdot x + 0.6 \cdot F_F$ |
| | 20 | $-0.25 \cdot x + 0.6 \cdot F_F$ |
| | 25 | $-0.65 \cdot x + 0.6 \cdot F_F$ |
| | 35 | $-0.75 \cdot x + 0.8 \cdot F_F$ |
| | 40 | $-0.7 \cdot x + 0.65 \cdot F_F$ |
| | 50 | $-0.8 \cdot x + 0.5 \cdot F_F$ |
| | 63 | $-0.8 \cdot x + 0.65 \cdot F_F$ |
| 80 | $-1.3 \cdot x + 0.6 \cdot F_F$ | |

| Gripping force retention | Size | F_{Ftotal} per gripper finger |
|--------------------------|---------------------------------|---------------------------------|
| G2 | 16 | $-0.05 \cdot x + 0.6 \cdot F_F$ |
| | 20 | $-0.5 \cdot x + 0.6 \cdot F_F$ |
| | 25 | $-0.65 \cdot x + 0.6 \cdot F_F$ |
| | 35 | $-0.15 \cdot x + 0.8 \cdot F_F$ |
| | 40 | $-0.6 \cdot x + 0.65 \cdot F_F$ |
| | 50 | $-0.15 \cdot x + 0.5 \cdot F_F$ |
| | 63 | $-1 \cdot x + 0.65 \cdot F_F$ |
| 80 | $-0.25 \cdot x + 0.6 \cdot F_F$ | |

Determining the actual gripping forces F_{Gr} per gripper finger for HGPD-...-G1 and HGPD-...-G2 as a function of application

The parallel grippers with integrated spring type HGPD-...-G1 (opening gripping force retention) and HGPD-...-G2 (closing gripping force retention) can be used as

- single-acting grippers
- grippers with supplementary gripping force and
- grippers with gripping force retention depending on requirements.

In order to calculate the available gripping forces F_{Gr} (per gripper jaw), the gripping force F_H and spring force F_{Ftotal} must be combined accordingly.

Application forces per gripper finger

Single-acting

Supplementary gripping force

Gripping force retention

- Gripping with spring force:

$$F_{Gr} = F_{Ftotal}$$

- Gripping with pressure force:

$$F_{Gr} = F_H - F_{Ftotal}$$

- Gripping with pressure and spring force:

$$F_{Gr} = F_H + F_{Ftotal}$$

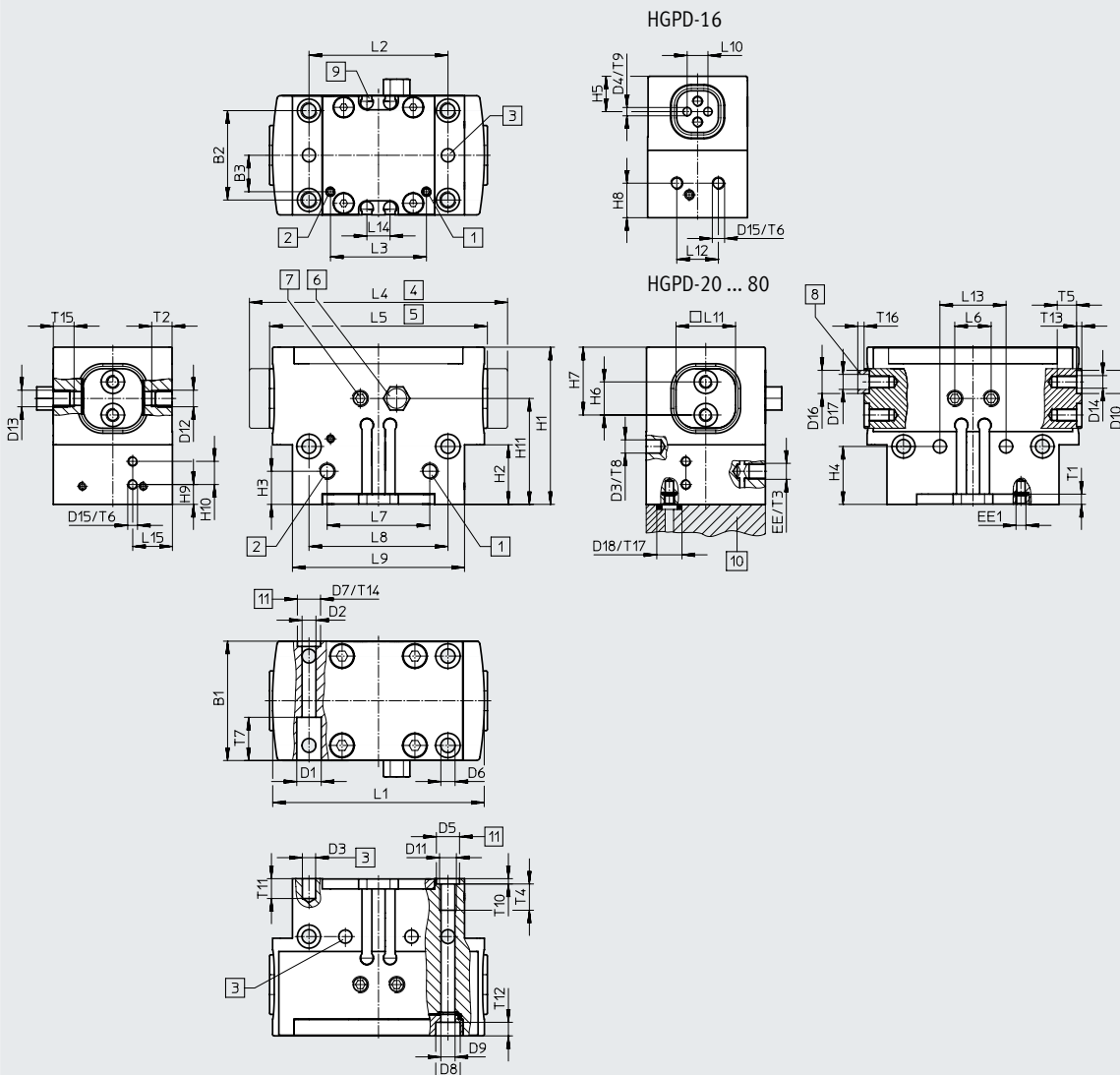
- Gripping with spring force:

$$F_{Gr} = F_{Ftotal}$$

Data sheet

Dimensions

Download CAD data → www.festo.com



- [1] Supply port, opening, either on the side or underneath (bottom port sealed on delivery)
- [2] Supply port, closing, either on the side or underneath (bottom port sealed on delivery)
- [3] Drilled hole for dowel pin (not included in the scope of delivery)
- [4] Gripper jaws open
- [5] Gripper jaws closed
- [6] Exhaust hole
- [7] Lubrication nipple (sealed on delivery)
- [8] Centring sleeves ZBH (4 included in the scope of delivery)
- [9] Slot for proximity switch
- [10] O-ring for parallel gripper
HGPD-20 ... 35: \varnothing 3x1
HGPD-40 ... 80: \varnothing 5x1.5
- [11] Drilled hole for centring sleeve ZBH

| Size | B1 | B2 ¹⁾ | B3 | D1 | D2 | D3 | D4 | D5 | D6 | D7 | D8 | D9 | D10 | D11 | D12 |
|------------------|------------|------------------|-----------|----------------------|---------------|---------------------|---------------------|---------------------|---------------|---------------------|----------------------|---------------|---------------------|-----|-----|
| [mm] | ± 0.05 | | ± 0.1 | \varnothing H13 | \varnothing | \varnothing H8 | \varnothing H8 | \varnothing H8 | \varnothing | \varnothing H8 | \varnothing H13 | \varnothing | \varnothing H8 | | |
| 16 | 24 | 17 | 4 | 4.6 | 2.6 | 2 | 2 | 5 | 2.6 | – | 4.6 | – | – | M3 | M3 |
| 20 ²⁾ | 28 | 22 | 8.7 | 5.6 | 3.2 | 3 | – | 5 | 3.2 | – | – | – | 5 | M4 | M3 |
| 25 | 36 | 27 | 11 | 7.4 | 4.2 | 4 | – | 7 | 4.2 | 7 | 7.4 | 4.3 | 7 | M5 | M5 |
| 35 | 42 | 32 | 13 | 9.2 | 5.2 | 4 | – | 7 | 4.2 | 7 | 7.4 | 4.3 | 9 | M5 | M5 |
| 40 | 50 | 38 | 17 | 10.4 | 6.2 | 5 | – | 9 | 5.2 | 9 | 9.4 | 5.3 | 9 | M6 | M5 |
| 50 | 60 | 45 | 20 | 13.5 | 8.2 | 6 | – | 12 | 6.1 | 12 | 10.4 | 6.4 | 12 | M8 | M5 |
| 63 | 72 | 56 | 24.5 | 13.5 | 8.4 | 6 | – | 12 | 6.4 | 12 | 10.4 | – | 12 | M8 | M5 |
| 80 | 100 | 70 | 39.5 | 18.5 | 12.2 | 8 | – | 12 | 8.5 | 15 | 13.5 | 8.4 | 15 | M10 | M5 |

1) Tolerance for centring hole ± 0.02 mm
Tolerance for thread ± 0.1 mm
2) Dowel pins [3] must be used when mounted from below.

Data sheet

| Size [mm] | D13 | D14 | D15 | D16 ∅ h7 | D17 ∅ | D18 ∅ +0.2 | EE | EE1 | H1 | | H2 | | H3 | |
|--------------|------|------|-----|----------------|----------|------------------|------|-----|-------|-------------|------|------|------|------------|
| | | | | | | | | | ±0.05 | -G ±0.05 | | -G | ±0.1 | -G ±0.1 |
| 16 | M3 | M2.5 | M3 | – | – | – | M5 | M3 | 34 | 41.5 | 16.2 | 23.6 | 12 | 12 |
| 20 | M3 | M3 | M3 | 5 | 3.2 | 5 | M5 | M3 | 39 | 46 | 15 | 22 | 10 | 15 |
| 25 | M5 | M4 | M3 | 7 | 5.3 | 5 | M5 | M3 | 47.5 | 55.5 | 18 | 26 | 10 | 20 |
| 35 | M5 | M6 | M3 | 9 | 6.4 | 5 | M5 | M3 | 57.5 | 74 | 21.5 | 38 | 12 | 23.5 |
| 40 | M5 | M6 | M3 | 9 | 6.4 | 8 | M5 | M3 | 67 | 85 | 27 | 45 | 15 | 36 |
| 50 | G1/8 | M6 | M3 | 12 | 10.3 | 8 | G1/8 | M5 | 77.5 | 102.5 | 32 | 57 | 15 | 30 |
| 63 | G1/8 | M8 | M3 | 12 | 10.3 | 8 | G1/8 | M5 | 94 | 124 | 39 | 69 | 18 | 26 |
| 80 | G1/8 | M10 | M3 | 15 | 12.4 | 8 | G1/4 | M5 | 110 | 146 | 48 | 84 | 22 | 33 |

| Size [mm] | H4 ¹⁾ | | H5 | H6 ¹⁾ | H7 | H8 | | H9 | | H10 | H11 | | L1 | L2 ¹⁾ | L3 |
|--------------|------------------|------|-------|------------------|-------|------|------------|------|------------|------|------|------|------|------------------|------|
| | | -G | -0.02 | | -0.02 | ±0.1 | -G ±0.1 | ±0.1 | -G ±0.1 | ±0.1 | ±0.1 | ±0.1 | ±0.1 | ±0.05 | |
| 16 | 17.5 | 24.5 | 8.5 | 5 | 11 | 8.3 | 15.8 | – | – | – | 25.5 | 33 | 50 | 29 | 22 |
| 20 | 14.5 | 21.5 | – | 7 | 15 | 6.5 | 13.5 | – | – | – | 27.5 | 34.5 | 50 | 35 | 22.6 |
| 25 | 17.5 | 26 | – | 10 | 20.5 | – | – | 6 | 14 | 7 | 32 | 40 | 64 | 42 | 29 |
| 35 | 20 | 37.5 | – | 12 | 24 | – | – | 9.5 | 26 | 7 | 39.5 | 56 | 80 | 52 | 39 |
| 40 | 25 | 42.5 | – | 15 | 28.5 | – | – | 15 | 33 | 8 | 46 | 64 | 101 | 66 | 47.4 |
| 50 | 30 | 55 | – | 18 | 32 | – | – | 15.5 | 40.5 | 8 | 54.5 | 79.5 | 126 | 82 | 61 |
| 63 | 28 | 68 | – | 24 | 40 | – | – | 26 | 56 | 8 | 66 | 96 | 161 | 100 | 75 |
| 80 | 34 | 76 | – | 24 | 42 | – | – | 35 | 71 | 8 | 80 | 116 | 201 | 130 | 82 |

| Size [mm] | L4 | L5 | L6 | L7 | L8 ¹⁾ | L9 | L10 | L11 | L12 | L13 | L14 | L15 | T1 | T2 | T3 |
|--------------|------|------|------|------|------------------|------|-------|-------|------|-------|------|------|------|------|------|
| | ±0.5 | ±0.5 | ±0.1 | ±0.1 | | ±0.1 | ±0.05 | -0.02 | ±0.1 | ±0.02 | +0.1 | ±0.1 | min. | min. | min. |
| 16 | 58 | 52 | 6.5 | 20 | 29 | 36 | 5 | 10 | 10 | 20 | 6 | – | 3 | 5.5 | 5.5 |
| 20 | 60 | 52 | 7.5 | 24 | 35 | 44 | – | 14 | 10 | 24 | 6 | – | 3 | 5.5 | 5.5 |
| 25 | 78 | 66 | 11 | 31 | 42 | 52 | – | 18 | – | 20 | 7 | 12 | 3 | 6.7 | 5.5 |
| 35 | 98 | 82 | 11 | 40 | 52 | 64 | – | 22 | – | 40 | 7 | 15 | 3 | 6.5 | 5.5 |
| 40 | 122 | 102 | 11 | 49 | 66 | 81 | – | 28 | – | 50 | 10 | 19 | 4 | 6.5 | 6.5 |
| 50 | 151 | 127 | 11 | 63 | 82 | 101 | – | 32 | – | 60 | 10 | 24 | 4 | 6.5 | 8.5 |
| 63 | 194 | 162 | 11 | 74 | 100 | 126 | – | 40 | – | 76 | 10 | 42 | 4 | 6.5 | 8.5 |
| 80 | 242 | 202 | 11 | 82 | 130 | 154 | – | 45 | – | 100 | 10 | 56 | 5.5 | 6.5 | 10 |

| Size [mm] | T4 | | T5 | T6 | T7 | T8 | T9 | T10 | T11 | T12 | T13 | T14 | T15 | T16 | T17 |
|--------------|------|------------|------|------|----|------|------|------|------|------|------|------|------|------|------|
| | min. | -G min. | min. | min. | | min. | +0.1 | +0.1 | min. | +0.2 | +0.1 | +0.1 | min. | -0.3 | +0.1 |
| 16 | 5.5 | – | 5 | 3.5 | 14 | 4.5 | 2.6 | 1.3 | 4 | 19.8 | – | – | 5.5 | – | – |
| 20 | 6.5 | – | 5 | 5 | 18 | 4 | – | 1.3 | 5 | 3 | 1.3 | – | 5.5 | 1.2 | 0.6 |
| 25 | 10.5 | – | 6 | 5 | 13 | 4.5 | – | 1.6 | 6 | 4.1 | 1.6 | 1.6 | 6.7 | 1.4 | 0.6 |
| 35 | 8.5 | – | 7.9 | 5 | 16 | 4.5 | – | 1.6 | 6 | 4.1 | 2.1 | 1.6 | 6.5 | 1.9 | 0.6 |
| 40 | 12.5 | – | 7.9 | 5 | 28 | 6 | – | 2.1 | 7 | 5.1 | 2.1 | 2.1 | 6.5 | 1.9 | 1.1 |
| 50 | 12.5 | – | 10 | 5 | 24 | 6 | – | 2.6 | 8 | 6.1 | 2.6 | 2.6 | 6.5 | 2.4 | 1.1 |
| 63 | 12.5 | – | 12 | 5 | 27 | 6 | – | 2.6 | 8 | 4.5 | 2.6 | 2.6 | 6.5 | 2.4 | 1.1 |
| 80 | 12.4 | 15 | 15 | 5 | 41 | 10 | – | 2.6 | 10 | 5.5 | 3.1 | 3.1 | 6.5 | 2.9 | 1.1 |

1) Tolerance for centring hole ±0.02 mm
Tolerance for thread ±0.1 mm

Data sheet

| Ordering data | | | | | | |
|---------------|---|-----------|--|--------------|---------------------|--------------|
| Size [mm] | Double-acting Without compression spring | | Single-acting or with gripping force retention | | | |
| | Part no. | Type | Opening Part no. | Type | Closing Part no. | Type |
| 16 | 1132936 | HGPD-16-A | 1132937 | HGPD-16-A-G1 | 1132938 | HGPD-16-A-G2 |
| 20 | 1132939 | HGPD-20-A | 1132940 | HGPD-20-A-G1 | 1132941 | HGPD-20-A-G2 |
| 25 | 1132942 | HGPD-25-A | 1132943 | HGPD-25-A-G1 | 1132944 | HGPD-25-A-G2 |
| 35 | 1132945 | HGPD-32-A | 1132946 | HGPD-32-A-G1 | 1132947 | HGPD-32-A-G2 |
| 40 | 1132948 | HGPD-40-A | 1132949 | HGPD-40-A-G1 | 1132950 | HGPD-40-A-G2 |
| 50 | 1132951 | HGPD-50-A | 1132952 | HGPD-50-A-G1 | 1132953 | HGPD-50-A-G2 |
| 63 | 1132954 | HGPD-63-A | 1132955 | HGPD-63-A-G1 | 1132956 | HGPD-63-A-G2 |
| 80 | 1132957 | HGPD-80-A | 1132958 | HGPD-80-A-G1 | 1132959 | HGPD-80-A-G2 |

Accessories



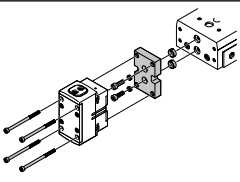
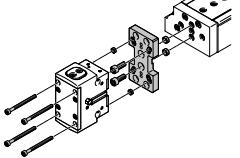
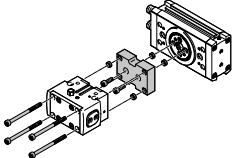
Adapter kit DHAA

Material:
Wrought aluminium alloy
Free of copper and PTFE
RoHS-compliant



Note

The kit includes the individual mounting interface as well as the necessary mounting material.

| Permissible drive/gripper combinations with adapter kit | | | | | | Download CAD data → www.festo.com | |
|---|-------------|--------------|---|---|-------------------------------|--|---------------------------|
| Combination | Drive size | Gripper size | Mounting option | | Adapter kit CRC ¹⁾ | Part no. | Type |
| | | |  |  | | | |
| DGST/HGPD | DGST | HGPD | | | DHAA | | |
|  | 10 | 16 | — | ■ | 2 | 8163132 | DHAA-G-G8-10-B12-16 |
| | 12 | 20 | — | ■ | | 8163129 | DHAA-G-G8-12-B12-20 |
| | 16 | 25 | — | ■ | | 8163133 | DHAA-G-G8-16-B12-25 |
| | 20 | 35 | — | ■ | | 8163131 | DHAA-G-G8-20-B12-35 |
| | 25 | 40 | — | ■ | | 8163130 | DHAA-G-G8-25-B12-40 |
| DGSL/HGPD | DGSL | HGPD | | | DHAA, HAPG | | |
|  | 8, 10 | 16, 20 | ■ | ■ | 2 | 564957 | DHAA-G-G6-8-B8-16 |
| | 12, 16 | 16, 20 | ■ | ■ | | 564954 | DHAA-G-G6-16-B8-16 |
| | 12, 16 | 25 | ■ | ■ | | 564952 | DHAA-G-G6-16-B8-25 |
| | 20, 25 | 25, 35 | ■ | ■ | | 537175 | HAPG-79 |
| | 20, 25 | 40 | ■ | ■ | | 564951 | DHAA-G-G6-20-B8-40 |
| DRRD/HGPD | DRRD | HGPD | | | DHAA | | |
|  | 12 | 16 | ■ | ■ | 2 | 2449935 | DHAA-G-Q11-12-B12-16 |
| | 12 | 20 | ■ | ■ | | 2449945 | DHAA-G-Q11-12-B12-20 |
| | 16 | 16 | ■ | ■ | | 2091914 | DHAA-G-Q11-16-B12/B12G-16 |
| | 16 | 20 | ■ | ■ | | 2091205 | DHAA-G-Q11-16-B12-20 |
| | 16 | 25 | ■ | ■ | | 2090715 | DHAA-G-Q11-16-B12-25 |
| | 20 | 25 | ■ | ■ | | 2088381 | DHAA-G-Q11-20-B12-25 |
| | 20 | 35 | ■ | ■ | | 2088008 | DHAA-G-Q11-20-B12-35 |
| | 25 | 35 | ■ | ■ | | 1714646 | DHAA-G-Q11-25-B12-35 |
| | 25 | 40 | ■ | ■ | | 1715576 | DHAA-G-Q11-25-B12-40 |
| | 32 | 40 | ■ | ■ | | 2092197 | DHAA-G-Q11-32-B12-40 |
| | 35 | 40 | ■ | ■ | | 2114998 | DHAA-G-Q11-35-B12-40 |
| | 32 | 50 | ■ | ■ | | 2124051 | DHAA-G-Q11-32-B12-50 |
| | 35, 40 | 50 | ■ | ■ | | 2124346 | DHAA-G-Q11-3 5/40-B12-50 |
| | 40 | 63 | ■ | ■ | | 2125614 | DHAA-G-Q11-40-B12-63 |
| | 50 | 63 | ■ | ■ | | 2352692 | DHAA-G-Q11-50-B12-63 |
| 50 | 80 | ■ | ■ | 2412840 | DHAA-G-Q11-50-B12-80 | | |

1) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

Accessories

Adapter kit
DHAA, HAPG

Material:
Wrought aluminium alloy
Free of copper and PTFE
RoHS-compliant



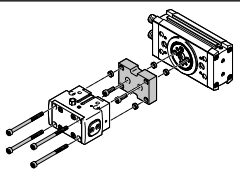
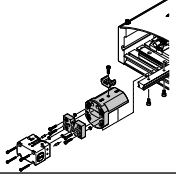


Note

The kit includes the individual mounting interface as well as the necessary mounting material.

Permissible drive/gripper combinations with adapter kit

Download CAD data → www.festo.com

| Combination | Drive size | Gripper size | Mounting option | | Adapter kit CRC ¹⁾ | Part no. | Type |
|--|-------------|-----------------------|---|---|-------------------------------|----------|---------------------------|
| | | |  |  | | | |
| DRRD/HGPD | DRRD | HGPD-...-G1/G2 | | | DHAA | | |
|  | 12 | 16 | ■ | ■ | 2 | 2798991 | DHAA-G-Q11-12-B12G-16 |
| | 12 | 20 | ■ | ■ | | 2800963 | DHAA-G-Q11-12-B12G-20 |
| | 16 | 20 | ■ | ■ | | 2642948 | DHAA-G-Q11-16-B12G-20 |
| | 16 | 25 | ■ | ■ | | 2642941 | DHAA-G-Q11-16-B12G-25 |
| | 20 | 25 | ■ | ■ | | 2642953 | DHAA-G-Q11-20-B12G-25 |
| | 20 | 35 | ■ | ■ | | 2642961 | DHAA-G-Q11-20-B12G-35 |
| | 25 | 35 | ■ | ■ | | 2642962 | DHAA-G-Q11-25-B12G-35 |
| | 25 | 40 | ■ | ■ | | 2642966 | DHAA-G-Q11-25-B12G-40 |
| | 32 | 40 | ■ | ■ | | 2642967 | DHAA-G-Q11-32-B12G-40 |
| | 32 | 50 | ■ | ■ | | 2642969 | DHAA-G-Q11-32-B12G-50 |
| | 35 | 40 | ■ | ■ | | 2643047 | DHAA-G-Q11-35-B12G-40 |
| | 35, 40 | 50 | ■ | ■ | | 2643100 | DHAA-G-Q11-3 5/40-B12G-50 |
| | 40 | 63 | ■ | ■ | | 2643055 | DHAA-G-Q11-40-B12G-63 |
| | 50 | 63 | ■ | ■ | | 2643096 | DHAA-G-Q11-50-B12G-63 |
| | 50 | 80 | ■ | ■ | | 2643098 | DHAA-G-Q11-50-B12G-80 |
| HSP/HGPD | HSP | HGPD | | | DHAA, HAPG | | |
|  | 12 | 16 | ■ | – | 2 | 564957 | DHAA-G-G6-8-B8-16 |
| | 16 | 16, 20 | ■ | – | | 540881 | HAPG-70-B |
| | | | | | | 564957 | DHAA-G-G6-8-B8-16 |
| | 25 | 16, 20 | ■ | – | | 540882 | HAPG-71-B |
| 564957 | 16 | 16 | ■ | – | 2 | 564957 | DHAA-G-G6-8-B8-16 |
| | | | | | | 540882 | HAPG-71-B |
| | | | | | | 564957 | DHAA-G-G6-8-B8-16 |
| | | | | | | 540882 | HAPG-71-B |

1) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

Accessories



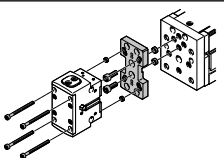
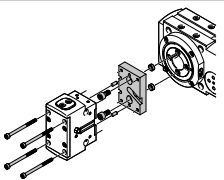
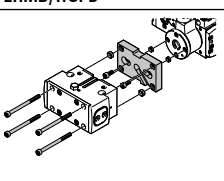
Adapter kit DHAA, HAPG

Material:
Wrought aluminium alloy
Free of copper and PTFE
RoHS-compliant

 **Note**

The kit includes the individual mounting interface as well as the necessary mounting material.

Download CAD data → www.festo.com

| Combination | Drive size | Gripper size | Mounting option | | Adapter kit CRC ¹⁾ | Part no. | Type |
|---|-------------|--------------|---|---|-------------------------------|----------|--------------------|
| | | |  |  | | | |
| EGSL/HGPD | EGSL | HGPD | | | DHAA, HAPG | | |
|  | 45, 55 | 25 | ■ | ■ | 2 | 564952 | DHAA-G-G6-16-B8-25 |
| | 75 | 25, 35 | ■ | ■ | | 537175 | HAPG-79 |
| | 75 | 40 | ■ | ■ | | 564951 | DHAA-G-G6-20-B8-40 |
| ERMB/HGPD | ERMB | HGPD | | | DHAA, HAPG | | |
|  | 20 | 25 | ■ | ■ | 2 | 537181 | HAPG-SD2-25 |
| | 20, 25 | 35 | ■ | ■ | | 537173 | HAPG-SD2-23 |
| | 25, 32 | 40 | ■ | ■ | | 537184 | HAPG-SD2-26 |
| | 32 | 50 | ■ | ■ | | 564956 | DHAA-G-Q5-32-B8-50 |
| EHMB/HGPD | EHMB | HGPD | | | DHAA, HAPG | | |
|  | 20 | 40 | ■ | ■ | 2 | 537184 | HAPG-SD2-26 |
| | 20, 25, 32 | 50 | ■ | ■ | | 564956 | DHAA-G-Q5-32-B8-50 |
| | 25, 32 | 63 | ■ | ■ | | 537188 | HAPG-SD2-28 |

1) Corrosion resistance class CRC 2 to Festo standard FN 940070

Moderate corrosion stress. Indoor applications in which condensation can occur. External visible parts with primarily decorative surface requirements which are in direct contact with a normal industrial environment.

Accessories

Gripper jaw blank BUB-HYPD

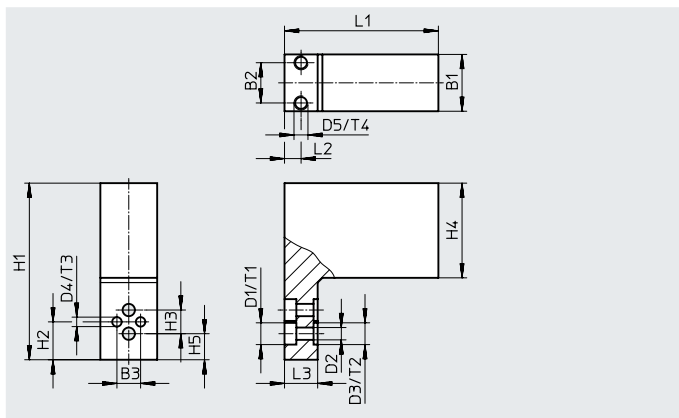
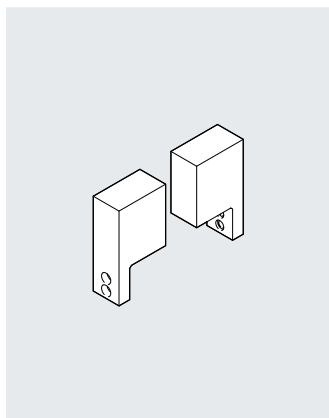
(2 included in the scope of delivery)

Material:

Wrought aluminium alloy

Free of copper and PTFE

RoHS-compliant



Dimensions and ordering data

| For size | B1 | B2 | B3 | D1 | D2 | D3 | D4 | D5 |
|----------|-------|-----|-------|----------|----------|---------|---------|----|
| [mm] | ±0.05 | | ±0.01 | ∅ H13 | ∅ H13 | ∅ H8 | ∅ H7 | |
| 16 | 12 | 8.5 | 5 | 4.6 | 2.6 | – | 2 | M3 |
| 20 | 14 | 8.5 | – | 5.9 | 3.2 | 5 | – | M3 |
| 25 | 20 | 14 | – | 7.4 | 4.3 | 7 | – | M3 |
| 35 | 29 | 23 | – | 10.4 | 6.4 | 9 | – | M3 |
| 40 | 32 | 26 | – | 10.4 | 6.4 | 9 | – | M3 |
| 50 | 35 | 26 | – | 10.4 | 6.4 | 12 | – | M3 |
| 63 | 40 | 26 | – | 13.5 | 8.4 | 12 | – | M3 |
| 80 | 44 | 26 | – | 16.5 | 10.5 | 15 | – | M3 |

| For size | H1 | H2 | H3 | H4 | H5 | L1 | L2 | L3 |
|----------|-------|-------|-----------------------|------|-----|-------|------|----|
| [mm] | ±0.05 | ±0.02 | | | | ±0.05 | | |
| 16 | 37.3 | 8 | 5±0.1 | 20 | – | 32.5 | 3.5 | 7 |
| 20 | 59 | – | 7±0.01 ¹⁾ | 35 | 8 | 35.5 | 3 | 10 |
| 25 | 76 | – | 10±0.01 ¹⁾ | 49.5 | 4.5 | 44.5 | 4.5 | 12 |
| 35 | 92.5 | – | 12±0.01 ¹⁾ | 59 | 7.5 | 52.5 | 6 | 12 |
| 40 | 110 | – | 15±0.01 ¹⁾ | 73.5 | 6 | 62.5 | 6 | 12 |
| 50 | 144 | – | 18±0.01 ¹⁾ | 99 | 11 | 78 | 10 | 15 |
| 63 | 171.5 | – | 24±0.01 ¹⁾ | 119 | 10 | 98.5 | 10.5 | 15 |
| 80 | 198 | – | 24±0.01 ¹⁾ | 139 | 15 | 120.5 | 10 | 20 |

| For size | T1 | T2 | T3 | T4 | Weight per blank [g] | Part no. | Type |
|----------|------|------|------|----|----------------------|----------------|--------------------|
| [mm] | +0.1 | +0.1 | +0.1 | | | | |
| 16 | 2.5 | – | 2.1 | 4 | 25 | 1180947 | BUB-HYPD-16 |
| 20 | 3.1 | 1.3 | – | 5 | 57 | 1180948 | BUB-HYPD-20 |
| 25 | 4.2 | 1.6 | – | 5 | 138 | 1180949 | BUB-HYPD-25 |
| 35 | 6.2 | 2.1 | – | 5 | 278 | 1180950 | BUB-HYPD-35 |
| 40 | 6.2 | 2.1 | – | 5 | 445 | 1180951 | BUB-HYPD-40 |
| 50 | 6.2 | 2.6 | – | 5 | 814 | 1180952 | BUB-HYPD-50 |
| 63 | 8.2 | 2.6 | – | 5 | 1340 | 1180953 | BUB-HYPD-63 |
| 80 | 10.2 | 3.1 | – | 5 | 2170 | 1180954 | BUB-HYPD-80 |

1) ±0.02 and ±0.01 apply to the centring hole D3
±0.1 applies to the through-holes D1 and D2

Accessories

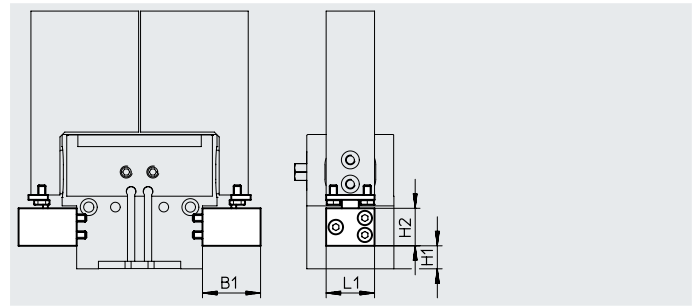
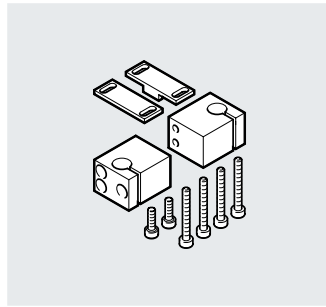
Sensor bracket DASI

(1 included in the scope of delivery)

Material:

Wrought aluminium alloy

RoHS-compliant



| Dimensions and ordering data | | | | | | | | |
|------------------------------|----|------|------|------|----|--------|----------|----------------|
| For size | B1 | H1 | | H2 | L1 | Weight | Part no. | Type |
| [mm] | | | -G | | | [g] | | |
| 16 | 18 | 4.3 | 11.8 | 8 | 18 | 25 | 1435225 | DASI-B12-16-S3 |
| 20 | 18 | 2.5 | 9.5 | 8 | 18 | 22 | 1435226 | DASI-B12-20-S3 |
| 25 | 24 | 1.5 | 9.5 | 15.5 | 20 | 50 | 1435227 | DASI-B12-25-S8 |
| 35 | 24 | 5 | 21.5 | 15.5 | 20 | 55 | 1435228 | DASI-B12-35-S8 |
| 40 | 29 | 11.2 | 29.2 | 15.6 | 20 | 65 | 1435229 | DASI-B12-40-S8 |
| 50 | 34 | 12 | 37 | 16 | 20 | 70 | 1435230 | DASI-B12-50-S8 |
| 63 | 54 | 22 | 52 | 16 | 20 | 95 | 1435231 | DASI-B12-63-S8 |
| 80 | 54 | 31 | 67 | 16 | 20 | 95 | 1435231 | DASI-B12-63-S8 |

| Ordering data | | | | | | |
|--|---------------|---|------------|----------|----------|------------------|
| | For size [mm] | Description | Weight [g] | Part no. | Type | PU ¹⁾ |
| Centring pin/sleeve ZBS/ZBH Data sheets → Internet: zbh | | | | | | |
| | 16 | For centring the gripper jaw blanks/gripper fingers on the gripper jaws | 1 | 525273 | ZBS-2 | 10 |
| | 20 | | 1 | 8146543 | ZBH-5-B | |
| | 25 | | 1 | 8146544 | ZBH-7-B | |
| | 35, 40 | | 1 | 8137184 | ZBH-9-B | |
| | 50, 63 | | 1 | 8137185 | ZBH-12-B | |
| | 80 | | 3 | 191409 | ZBH-15 | |
| | 16, 20 | For centring the gripper during mounting | 1 | 8146543 | ZBH-5-B | |
| | 25, 35 | | 1 | 8146544 | ZBH-7-B | |
| | 40 | | 1 | 8137184 | ZBH-9-B | |
| | 50, 63, 80 | | 1 | 8137185 | ZBH-12-B | |
| Blanking plug B Data sheets → Internet: blanking plug | | | | | | |
| | 16, 20 | For sealing the supply ports | 1 | 30979 | B-M3-S9 | 10 |
| | 25, 35, 40 | | 1 | 174308 | B-M5-B | |
| | 50, 63 | | 5 | 3568 | B-1/8 | |
| | 80 | | 15 | 3569 | B-1/4 | |

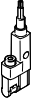
1) Packaging unit

Accessories

Proximity switch for size 16 ... 35

Ordering data – Proximity switch for C-slot, magneto-resistive


Data sheets → Internet: smt

| | Type of mounting | Electrical connection, outlet direction of connection | Switching output | Cable length [m] | Part no. | Type |
|--|--------------------------------------|--|---------------------|---------------------|----------|---------------------------|
| N/O contact | | | | | | |
|  | Insertable in the slot lengthwise | Cable, 3-wire, lateral | PNP | 2.5 | 547862 | SMT-10G-PS-24V-E-2.5Q-OE |
| | | Plug M8x1, 3-pin, lateral | | 0.3 | 547863 | SMT-10G-PS-24V-E-0.3Q-M8D |
| | | Cable, 3-wire, lateral | NPN | 2.5 | 8065030 | SMT-10G-NS-24V-E-2.5Q-OE |
| | | Plug M8x1, 3-pin, lateral | | 0.3 | 8065029 | SMT-10G-NS-24V-E-0.3Q-M8D |

Proximity switch for size 40 ... 80



Ordering data – Proximity switch for T-slot, magneto-resistive

Data sheets → Internet: smt

| | Type of mounting | Electrical connection, outlet direction of connection | Switching output | Cable length [m] | Part no. | Type |
|--|--------------------------------------|--|---------------------|---------------------|----------|--------------------------|
| N/O contact | | | | | | |
|  | Insertable in the slot lengthwise | Cable, 3-wire, lateral | PNP | 2.5 | 547859 | SMT-8G-PS-24V-E-2.5Q-OE |
| | | Plug M8x1, 3-pin, lateral | | 0.3 | 547860 | SMT-8G-PS-24V-E-0.3Q-M8D |
| | | Cable, 3-wire, lateral | NPN | 2.5 | 8065028 | SMT-8G-NS-24V-E-2.5Q-OE |
| | | Plug M8x1, 3-pin, lateral | | 0.3 | 8065027 | SMT-8G-NS-24V-E-0.3Q-M8D |

Ordering data – Connecting cables


Data sheets → Internet: nebu

| | Electrical connection, left | Electrical connection, right | Cable length [m] | Part no. | Type |
|--|------------------------------|------------------------------|---------------------|----------|---------------------|
|  | Straight socket, M8x1, 3-pin | Cable, open end, 3-wire | 2.5 | 541333 | NEBU-M8G3-K-2.5-LE3 |
| | | | 5 | 541334 | NEBU-M8G3-K-5-LE3 |
|  | Angled socket, M8x1, 3-pin | Cable, open end, 3-wire | 2.5 | 541338 | NEBU-M8W3-K-2.5-LE3 |
| | | | 5 | 541341 | NEBU-M8W3-K-5-LE3 |

Proximity switch for size 16, 20

Ordering data – Proximity switch 3 mm (round design), inductive


Data sheets → Internet: sieh

| | Electrical connection | LED | Switching output | Cable length [m] | Part no. | Type |
|--|-----------------------|-----|---------------------|---------------------|----------|----------------|
| N/O contact | | | | | | |
|  | Cable, 3-wire | ■ | PNP | 2.5 | 538264 | SIEH-3B-PS-K-L |
| | Plug M8x1, 3-pin | ■ | PNP | – | 538263 | SIEH-3B-PS-S-L |

Proximity switch for size 25 ... 80



Ordering data – Proximity switch M8 (round design), inductive

Data sheets → Internet: sien

| | Electrical connection | LED | Switching output | Cable length [m] | Part no. | Type |
|--|-----------------------|-----|---------------------|---------------------|----------|-----------------|
| N/O contact | | | | | | |
|  | Cable, 3-wire | ■ | PNP | 2.5 | 150386 | SIEN-M8B-PS-K-L |
| | Plug M8x1, 3-pin | ■ | PNP | – | 150387 | SIEN-M8B-PS-S-L |

Ordering data – Connecting cables

Data sheets → Internet: nebu

| | Electrical connection, left | Electrical connection, right | Cable length [m] | Part no. | Type |
|--|------------------------------|------------------------------|---------------------|----------|---------------------|
|  | Straight socket, M8x1, 3-pin | Cable, open end, 3-wire | 2.5 | 541333 | NEBU-M8G3-K-2.5-LE3 |
| | | | 5 | 541334 | NEBU-M8G3-K-5-LE3 |
|  | Angled socket, M8x1, 3-pin | Cable, open end, 3-wire | 2.5 | 541338 | NEBU-M8W3-K-2.5-LE3 |
| | | | 5 | 541341 | NEBU-M8W3-K-5-LE3 |